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Precision Planting SmartDepth Evaluation for Assessing Seeding Depth Accuracy and Row-to-Row Variability

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Planter Technology Trends

- Timely and uniform emergence is important for optimal stand establishment
- Increased interest in improving planter performance (i.e. seed metering and placement accuracy)
- Numerous advanced planting technology options available today to utilize.



Precision Planting SmartDepth

- Allows depth changes from the cab as field conditions change
- Removes row-to-row depth variability (same depth across the whole planter)
- Precise depth especially for shallow seeded crops (e.g. cotton)



Evaluate performance (accuracy & row-to-row variability) of Precision Planting SmartDepth system



6-row John Deere MaxEmerge XP Planter

PP vDrive



PP DeltaForce





PP SmartDepth



PP 20 20 Gen 3



Treatments & Layout

• A variable depth prescription (Rx) map:

- Five corn seeding depths (1.50, 1.75, 2.00, 2.25 and 2.50 in.)
- Each depth replicated 5 times & randomized within the field
- All possible depth transitions included (e.g. 1.50 1.75 in.) during planting
- Rx map uploaded into the 20|20 display and implemented:
 - SmartDepth was calibrated using PP's recommended procedure
 - All other planting parameters remained constant (e.g. seeding rate, speed, etc.)



Data Collection

Seed depth measurements -

- all 6 planter rows
- 20 randomly selected plants within each row
- depth measured up to accuracy of 1/16 inch







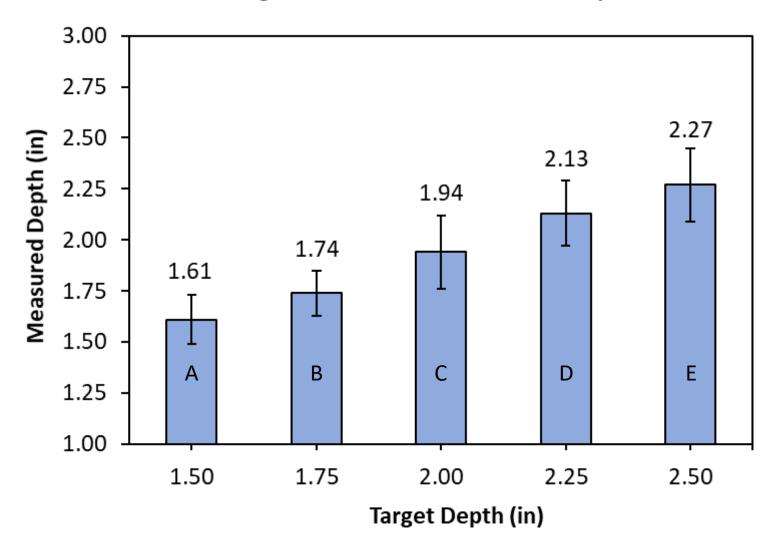
Data Collection

Transition distance –

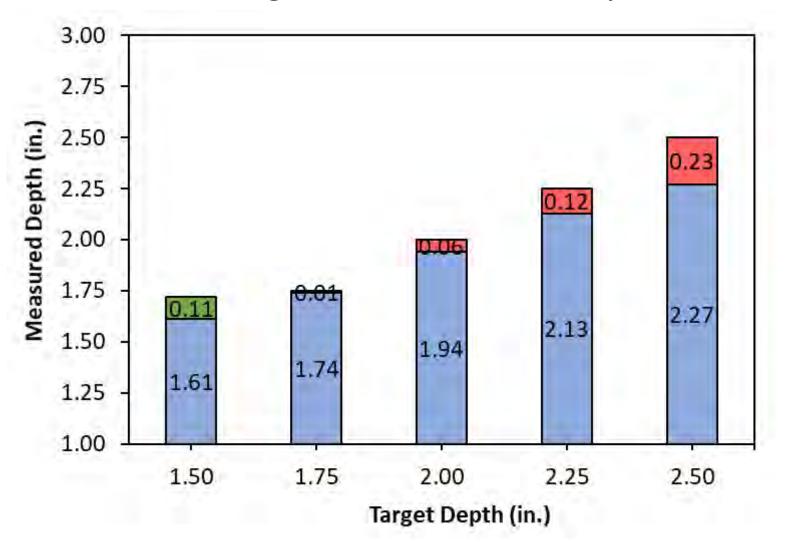
- Transition locations for depth changes were marked using RTK GPS
- A distance of 5 ft prior to the transition and 10 ft after the transition (rows 3 and 4) was marked
- Depth was measured for all plants in the transition zone (15 ft)



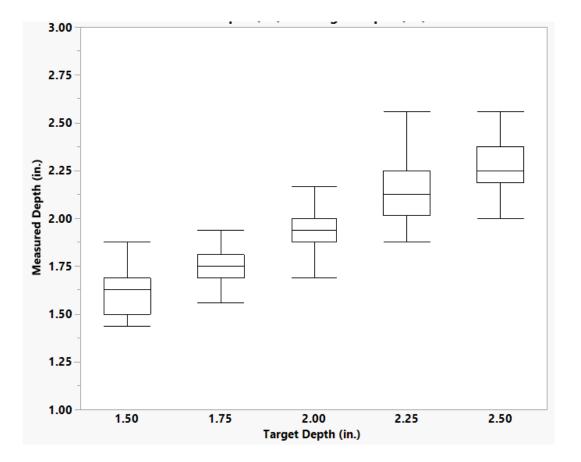
System Accuracy Target vs Measured Depth



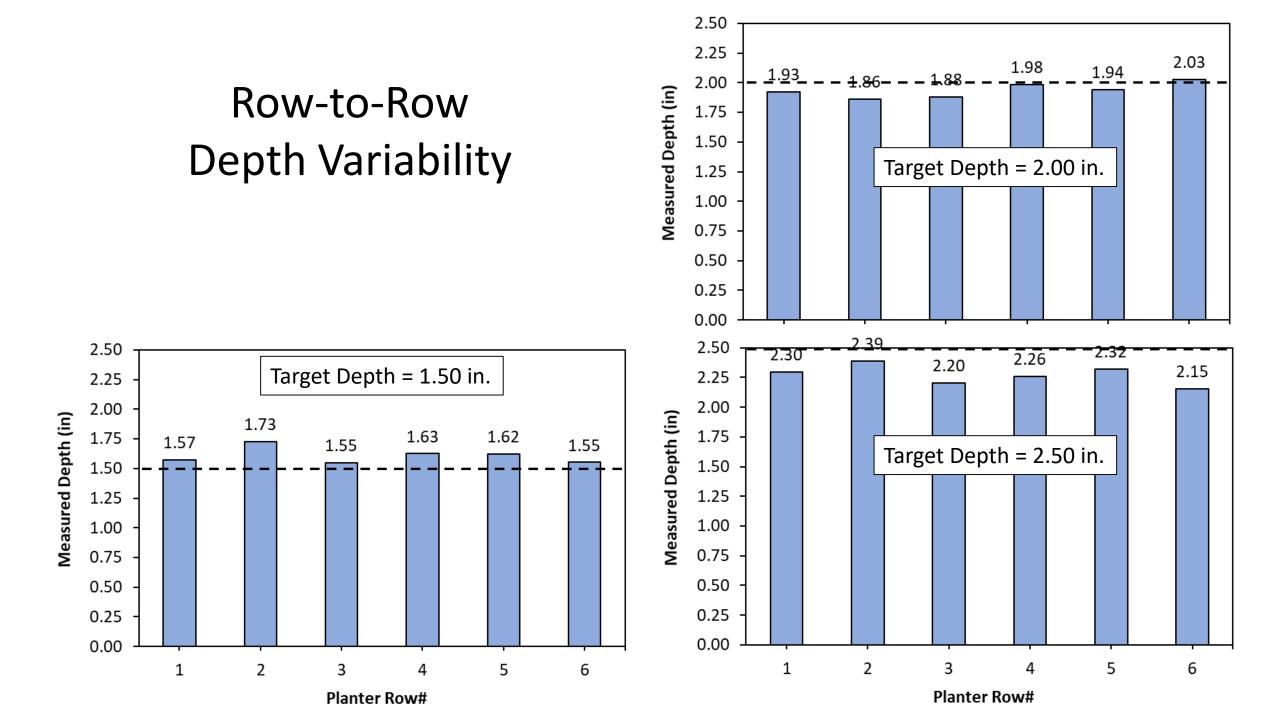
System Accuracy Target vs Measured Depth



PP SmartDepth System - CV & Accuracy



Target (in.)	Measured (in.)	CV (%)	Accuracy (%)
1.50	1.61	8	93
1.75	1.74	6	99
2.00	1.94	9	97
2.25	2.13	7	95
2.50	2.27	8	91



Row-to-Row – Depth Variability

Mean Depth (in.)

Pow#	Target Depth (in.)				
Row#	1.50	1.75	2.00	2.25	2.50
1	1.57	1.66	1.93	1.97	2.30
2	1.73	1.74	1.86	2.22	2.39
3	1.55	1.75	1.88	2.18	2.20
4	1.63	1.77	1.98	2.21	2.26
5	1.62	1.75	1.94	2.13	2.32
6	1.55	1.72	2.03	2.09	2.15
Planter	1.61	1.74	1.94	2.13	2.27

CV (%)

Row#	Target Depth (in.)				
KOW#	1.50	1.75	2.00	2.25	2.50
1	5.3	6.9	6.6	7.9	5.6
2	5.2	4.3	12.8	3.4	5.9
3	8.1	4.2	7.2	10.7	4.7
4	9.9	9.4	4.9	4.4	5.7
5	6.0	3.8	3.7	5.0	6.1
6	6.7	5.3	12.8	4.9	14.2
Planter	7.7	6.1	9.1	7.5	8.1

Depth Transition Distance

Depth Increment/decrement (in.)	Transition Distance (ft)	
0.25	1.9 – 3.6	
0.50	2.3 – 4.1	
0.75	2.9 – 4.4	
1.00	3.2 – 4.9	

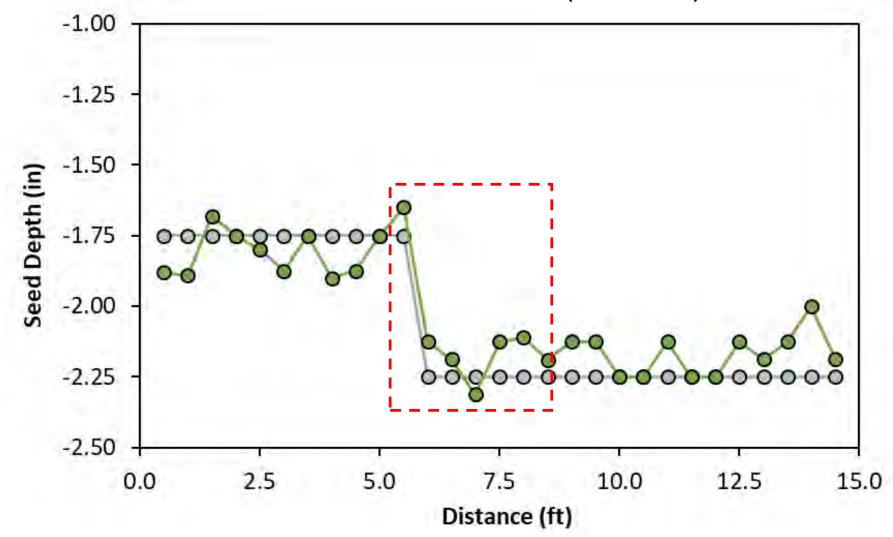
All depth transitions occurred within less than 5 ft.

Planting speed = 4.5 mph (6.6 fts)

Transition time = 0.76 sec

System Response - Rate Transitions

1.75 – 2.25 inch (0.50 inch)



Summary

> System Accuracy:

- The PP SmartDepth system was able to achieve the target seeding depths with
 >90% accuracy. Actual seeding depth was always shallower for 2.0 2.5 in.
- Row-to-row depth variability was mostly low across all seeding depths (CV < 10%).

> System Response:

 Transition between seeding depths were quick (< 5 ft) indicating fast response time of the SmartDepth system (≤ 0.76 sec).

Future Work: Analyze cotton and peanut data to compare trends noticed in corn. Evaluate influence of tillage and soil type on system accuracy.

Thanks!

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